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Research Article

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The study of methods to get irregular surfacetopography and its impact on friction performance

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ABSTRACT

To get irregular surface topography efficiently, various processing methods were compared and the chemical etching method, which is simple to operate and cheap to use was chosen to process the irregular surface topography of cold work die steel Cr12. Then the relationship between the surface topography and the corrosive agents as well as the corrosion time was analyzed. Different kinds of corrosive agents resulted in different surface topography under the same corrosion time and the stronger the corrosivity was, the shorter time it took to get corrosion pits, which enhanced the sensibility to corrosion time. To research the impact of irregular surface topography on the friction performance of die surface, wear tests of samples with both smooth surface and irregular surface topography was performed under starved-oil lubrication. After analyzing the friction coefficient of twelve specimens, conclusions can be drawn as follows: irregular surface topography can reduce the friction coefficient of die surface effectively; the value of friction coefficient has a strong relationship with the density of contact peaks and, under certain surface topography, the denser the contact peaks are, the smaller the friction coefficient is; the friction coefficient increases first, and then decreases when the corrosion pits get bigger and deeper.

Keywords: irregular surface topography; corrosion pits; starved-oil lubrication; friction coefficient.

INTRODUCTION

The die is a kind of fundamental processing equipment which plays a crucial role in industrial production. Due to the advantages of moulds such as mass production, nice consistence, high efficiency and low cost etc., mould industry has become one significant guideline estimating the national manufacturing industry [1]. The friction performance of die surface is of great importance for the quality and production of our products. Meanwhile, it also has vital impact on the carrying capacity and service life of moulds. Therefore, to improve the product's quality as well as efficiency and to decrease the cost of production, it is quite urgent to reduce the frictionalwear. In recent years, plenty of research finds have confirmed the validity of reasonable surfacetopography on lowering the friction, reducing the frictional wear and improving the carrying capacity [2-4]. Some common methods to get surfacetopography include laserprocessing, chemical etching, electrical discharge machining and electrochemical machining etc. Laser processing technology is based on the interaction between laser beam and materials (including metal and non-metal) and it is widely used in the incising, welding, surfacetreatment, punching and micromachining process. There are no contact and no frictional resistance between tools and workpieces, which makes laser processing fast, noiseless and less susceptible to heat. Some practical cases of rectangular, sagittal or circular micro-texturing got by laser processing are as follows: Shuting Lei from Kansas State University adopted laserprocessing to produce micro holes on the rake face of uncoated tungsten carbide (WC) cutting inserts. The cutting forces (Ff,Ft, and Fc) are reduced by 10-30% with micro pool lubrication and the chip-tool contact length is reduced by about 30% [5]. Bart Raeymaekers and Izhak Etsion from Center for Magnetic Recording Research, University of California San Diego reduced the friction coefficient between guides and magnetic

tape by laser surface texturing the cylindrical guides[6]. Yang Li and Xiaojun Liu from HefeiUniversityofTechnology used Laser Surface Texturing technology to produce samples with various shapes, depth, spacing and area share and studied the impact of micro-texturing on the friction coefficient under different rotation rate and load cases[7]. Chemical reaction or physical bumps are used in chemical etching technology to remove the materials. The chemical etching technology is often applied in solar battery preparation process to get fluffy surface which can enhance the reflection areas. It is also used in frictional performance research to produce surface pits of different shapes. There are plenty of advantages of chemical etching method which include lower facilityrequest, simpler operating process and faster acquisition of micron-sized rough structure. A case in point can be that Jinfeng Li and Xiaolei used chemical etching method to produce surface micro-texturing and researched the impact of micro-texturing on the friction coefficient under water lubrication [8]. Zhengguo Wang and Jiliang Mo from the Tractive power National key Laboratory studied the impact of the size and distribution of grooved type micro-texturing on the friction and noise by producing grooves of different width and spacing on brake disks [9]. The electrochemical machining technology is a kind of non-traditional machining method which is based on the anodic dissolution theory and the metal anode will dissolve to certain shapes in electrolytic solution. Jung Won Byun from Seoul National University adopted micro ECM method to produce micro features for friction reduction [10]. This method has also been used to produce surface micro-texturing by Zhanhe Wang, Yongwei Zhu from YangzhouUniversity and Wei Liu from Nanjing University of Aeronautics and Astronautics [11-12]. Some other ways can also be used to get surface topography: Rendi Kurniawan et al. found that surface texturing can be produced by applying piezoelectric tool holder actuator on conventional CNC turning[13]; Micro ball end milling method was used by Eldon Graham et al. from University of Calgary to get Micro-Dimpled surfaces[14].

The processing methods mentioned above can meet the requirement of the surface texture machining of various materials on the whole. However, the special equipment, high machining cost or restricted dimension of finished surface etc. render these methods unbefitting. In this paper, the immersion corrosion method was adopted to get irregular surface topography due to its simple operation, low cost and unrestricted dimension of finished surface.

EXPERIMENTAL SECTION

Materials and processes

For the subsequent research of frictional performance of samples' surface, cold work die steel Cr12 was chosen as the sample materials and the dimension of samples is $30 \text{mm} \times 10 \text{mm} \times 5 \text{mm}$. There are three kinds of corrosive agents: A(aquaregia), B(mixed solution of ferric chloride, nitric acid and distilled water and their ration is 20g: 30 ml: 10 ml), C(supersaturated solution of ferric chloride in hydrochloric acid). Before our tests, the specimens were polished by abrasivepaperformetallograph $400^{\#} \times 600^{\#} \times 1200^{\#} \times 2000^{\#}$ in sequence and then they were polished on polishingmachine to get the surface roughness about 0.08. After polishing process, the specimens were cleaned by the ultrasonic cleaner and the cleaning reagent used was anhydrous ethanol. At last, the corrosive agents for different soaking time.



Fig1. Corrosion process

Testing principles

Metal's corrosion in acid solution is an electrochemical process. Electric potential difference occurs in various regions of solution where the local impurity concentration difference or tiny defects and damages exist. Because of the lower electric potential at defects area or where the local impurity concentration is high, many micro batteries take shape on the surface of metal, which promotes the corrosion of metal's surface.

The reaction equation of samples in corrosive agent A: $4HNO_3 + F_e = F_e(NO_3)_3 + 2H_2O + NO\uparrow$

The reaction equation of samples in corrosive agent B: $F_e + 2F_eCl_3 = 3F_eCl_2$

$$3F_{e}Cl_{2}+4HNO_{3} = 2F_{e}Cl_{3} + F_{e}(NO_{3})_{3} + NO^{+2}H_{2}O$$

The reaction equation of samples in corrosive agent C: $F_e + 2F_eCl_3 = 3F_eCl_2$

$$F_{e} + 2HCl = F_{e}Cl_{2} + H_{2}$$

RESULTS AND DISCUSSION

The impact of corrosive agents and corrosion time on the surfacetopography of samples

Figure 2-5 show the scanning electron microscopic image of samples' surfacetopography. Figure 2 shows the surfacetopography of sample0[#] which was grinded smooth and done no corrosion process; Figure 3 shows the surfacetopography of sample $A1^{\#}$, $A2^{\#}$, $A3^{\#}$ which were corroded in corrosive agent A for 10mins, 15mins and 20mins,respectively;Figure 4 shows the surfacetopography of sample $B1^{\#}$, $B2^{\#}$, $B3^{\#}$, $B4^{\#}$, $B5^{\#}$ which were corroded in corrosive agent B for 5mins, 10mins, 15mins, 20mins and 25mins,respectively; Figure 5 shows the surfacetopography of sample $C1^{\#}$, $C2^{\#}$, $C3^{\#}$ which were corroded in corrosive agent C for 20mins, 30mins and 60mins,respectively; Figure 5 shows the cutting height of each sample along vertical direction after filteringprocessing, which indicates the depth of corrosion pits on the samples surface.

From Fig.3 we can see that, because of the corrosion pits of uneven size which result from chemical reaction between sample surface and corrosive agent A, the surfacetopography of sample $A1^{\#}$, $A2^{\#}$, $A3^{\#}$ is not smooth enough. Meanwhile, the size of corrosion pits experiences an incline from $A1^{\#}toA3^{\#}$, which demonstrates that the size of corrosion pits and the corrosion time are directlyproportional in corrosive agent A. Compared to Fig.3, the corrosion pits in Fig.4 tends to be much bigger and evenly distributed.

The corrosion pits on sample $B1^{\#}$, $B2^{\#}$, $B3^{\#}$, $B4^{\#}$, $B5^{\#}$ are of uneven size, which indicates the coherence of corrosion pits' size and corrosion time. However, the size of corrosion pits experiences a larger fluctuation rather than growing continually with the corrosive time increasing. In particular, the corrosion pits after 10mins' corrosion are much bigger than that of 5mins' but they tend to be less obvious when the corrosion time is 15mins. The reason for this phenomenon can be that the chemical reaction on sample surface is almost full, which makes the surface smoother. When the corrosion time increases to 20mins, the corrosion pits appear to be obvious and uniformly distributed again and then they tend to be smooth once again at 25mins.

Fig.5 shows the corrosion processing done in corrosive agent C, which lasts longer time than that in corrosive agent A and B. From Fig.5 we can see that the corrosion pits are shallow and elliptic and their size tends to be homogeneous, which proves the independence of corrosion time and corrosion pits' size in corrosive agent C. The strongest chemical reaction can be found in corrosive agent B which is followed by A and C and it takes less time for corrosion processing in B. What is more, the corrosion pits got from corrosive agent B and C tend to have relatively more regular shape than A.



Fig.2surface topography of sample 0[#]





Fig.5 surface topography of samples corroded in corrosive agent C

Fig.6 shows the two-dimensional profile of certain cross section of each sample along its longitudinal direction and Table 1 shows the height values and the average friction coefficient of each profile in Fig.6. Fig.6 and Table1 indicate that the height values of sample $0^{\#}$ are much smaller than that of any other samples. Meanwhile, because of the smoother surface of sample $1^{\#}$, the height values of it are basically the same while some deeper corrosion pits can be found in other samples. After comparing the depth of corrosion pits in three groups' samples, we found the strong and weak relationship among corrosive agents: B>A>C. Therefore, corrosive agent B can be employed to get bigger and deeper corrosion pits and due to the less impact of corrosive agent C on corrosion pits, using corrosive agent C is of more convenience to control the corrosion time in our experiment.

Fig.7 shows the relationship between the depth of corrosion pits and the corrosion time. From Fig.7 we can see that both the corrosion time and the categories of corrosive agents have influence on the depth of corrosion pits. Within certain corrosion time, the longer time the samples are corroded in the corrosive agent A or C, the deeper the corrosion pits are. However, the depth of corrosion pits in corrosive agent B shares a tendency as follows: increasing \rightarrow decreasing \rightarrow decreasing \rightarrow decreasing, which can be explained by the same reason for the size of corrosion pits changing with corrosion time.





- (j) two-dimensional profile of C1[#]
- (k) two-dimensional profile of C2[#]
- (1) two-dimensional profile of $C3^{\#}$

Fig.6 two-dimensional profile of each sample along its longitudinal direction

Table1 the height values and the average friction coefficient of each profile in Fig.6

			14.00	
No.	the maximum	the minimum	differenc	the average friction
	height	height	e	coefficient
$0^{\#}$	7.36894	7.03686	0.33208	0.199
A1 #	34.69	0.04	34.65	0.146
A2 #	48.31	0.03	48.28	0.086
A3 #	200.78	130.05	70.73	0.099
$B1^{\#}$	62.40824	0.21419	62.19405	0.089
$B2^{\#}$	67.49212	1.21897	66.27315	0.112
B3 [#]	89.52051	52.62589	36.89462	0.113
$B4^{\#}$	83.60765	0.26541	83.34224	0.201
$B5^{\#}$	38.97605	0.91158	38.06447	0.095
C1 [#]	8.54264	5.25557	3.28707	0.152
C2#	10.68644	3.26561	7.42083	0.151
C3 [#]	12.01369	4.43481	7.57888	0.142



(a) (b) (c) (a) in corrosive agent A (b) in corrosive agent B (c) in corrosive agent C Fig.7the relationship between the depth of corrosion pits and the corrosion time

The impact of surfacetopography on frictional coefficient

Our experiment was done on HSR-2M high-speed reciprocating friction test machine(shown in Fig.8) and the two testspecimens used were GCr15(Φ 6,sphere,HRC65) and Cr12(30mm×10mm×5mm,cuboid). The upper specimen moves in a straight line relative to the lower one twice in each round of the motor and starved-oil lubrication was adapted, which means that we only coat a very thin oil film (5[#]engineoil from Hasitai Lubricatingoil Co. Limited) on the lower specimen surface at the very beginning. Other parameters are as follows: the friction load is 150N; the motor speed is 300r/min; the grindingcrack length is 10mm; the friction time is 5mins.



Fig .8 HSR-2M high speed reciprocating friction test machine

Fig.9 shows that how the friction coefficient changes as a function of friction time. From Fig.9 we can see that the friction coefficient of all samples surface, except for $B4^{\#}$, is lower than that of $0^{\#}$ after corrosion processing. What is more, the friction coefficient of sample $0^{\#}$ increases considerably with corrosion time arising while that of other samples which were corroded keeps relatively stable. Therefore, a surface with certain topography can reduce much more friction coefficient than a smooth surface under starved-oil lubrication. The friction coefficient curve of samples corroded in corrosive agent C experiences a much greater fluctuation than that in corrosive agent A and B. In addition, Table 1 indicates that the average friction coefficient is as below:

$$\varphi = \frac{f_n - f_1}{f_1} \times 100\%$$
(1)
$$f_n = \frac{f_n - f_1}{f_1} \times 100\%$$
(1)

 f_1 ——sample 1[#]'s friction coefficient.

The friction coefficient is related to the surfacetopography of samples. The friction coefficient of samples with irregular surfacetopography all tends to be smaller than that of samples with smooth surface, except for B4[#], which proves the effectiveness of irregular surface topography of reducing the frictional wear and lowering the friction coefficient. The reason for this phenomenon can be that the corrosion pits in the irregular surface topography can not only store more lubricatingoil for boundarylubrication or start-up friction surface but also store the wear debris to alleviate ploughing wear and to reduce frictionalresistance.

Fig.10 shows the relationship between the friction coefficient as well as its reductionrate and the depth of corrosion pits. Samples corroded in corrosive agent C have shallower corrosion pits than those in A and B and the friction coefficient decreases with the corrosion pits getting deeper. Meanwhile, the friction coefficient of samples corroded in corrosive agent A and B decreases firstly, and then increases when the depth of corrosion pits increases, which proves the impact of the depth of corrosion pits on friction coefficient. From the experiments we can know that there is an optimal range of corrosion pits' depth for the friction coefficient reduction rate and it is the pits of 36-70 um see the biggest friction coefficient reduction rate. The reason can be that the bigger and deeper the corrosion pits with same depth, the carrying capacity of oil film declines when the area of corrosion pits is too large, which results in the decreasing number of contact peaks per unit contact area. Then each contact peak has to bear more loads, which increases the plastic contact rate and the friction coefficient. What is more, when the size and area of corrosion pits are the same, then more

B4[#]

B5*

0#

lubricating oil will be stored with the pits getting deeper. However, the deeper the pits are, the longer distance the lubricating oil has to flow from bottom to the contact surface, which weakens the fluidity of the lubricating oil and the beneficial influence of corrosion pits.

Sample $A2^{\#}$ sees the best friction coefficient reduction rate (56.8%) and its corrosion pits' depth is within the optimal range we recommend (36—70 μ m). The shape of sample A2[#] is relatively uniform and the number of contact peak per unite area is bigger than other samples, which makes $A2^{\#}$ more effective on anti-friction performance.



Fig.9the changing curve of friction coefficient with friction time





Fig.10 the relationship between the friction coefficient as well as its reductionrate and the depth of corrosion pits

CONCLUSION

1) The chemical corrosion method can be adapted to get irregular surface topography of samples

2) The irregular surface topography can reduce the friction coefficient effectively in starved-oil lubrication and the friction coefficient reduction rate can be as high as 56.8% compared to smooth surface.

3) The friction coefficient of certain sample surface has a close relation with the density of surface contact peak. When the lubrication and surface topography are definite parameters, the denser the contact peak is, the less load each contact peak has to bear. Therefore, the frictional resistance, the friction coefficient and the wear mass loss all decrease.

4) The friction coefficient is related to the size and depth of corrosion pits and it declines first, and then increases when the corrosion pits get bigger or deeper.

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