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# Comparison of impedance analysis and field analysis in eddy current testing

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## ABSTRACT

This paper presents the theoretical basis of eddy current testing. Firstly, it introduces the impedance analysis method used in the field of eddy current testing. Then we analyze the skin effect and the phase lag on that basis. Next we introduce the field analysis method in eddy current testing. This article takes the Maxwell's equations of time-harmonic electromagnetic field as a starting point and then describes both the equations and their boundary value problems with vector magnetic potential, and it studies the perturbed magnetic field caused by ideal defects on that basis. Finally, this paper analyzes and contrasts the impedance analysis method and the field analysis method in depth.

Key words: Eddy current; nondestructive testing; impedance analysis; field analysis

## **INTRODUCTION**

Eddy Current Testing (ECT) [1-3] is a new non-destructive testing technology, which is based on Faraday's law of electromagnetic induction and Maxwell's equations [4-6]. In the process of ECT, when the coil with sinusoidal alternating current closes to the measured conductor, the electromagnetic induction occurs due to the interaction between the excitation electromagnetic field generated by coil and the measured conductor. The eddy current interlinks the excitation electromagnetic field induces in external and internal layers of a test piece. Meanwhile, the eddy current engenders corresponding alternating electromagnetic field as well and reacts upon the original magnetic field changing more and more quickly, the induced electromotive force external and internal the conductor increases and so does the induced eddy current. There are many influencing factors on eddy current as well as the methods to analyze eddy current testing: the impedance analysis method and the field analysis method, and makes analysis and contrast on the two methods in detail, which lays a solid theoretical foundation in the research in subsequent chapter.

## EDDY CURRENT TESTING BASED ON IMPEDANCE ANALYSIS

In the field of ECT, detection signal comes from the variation of detecting coil impedance or the changes of secondary coil's induced voltage. As there are many factors affect impedance and voltage and influence degree by these factors are different, there must have the means and methods to eliminate interference factors of extracting a meaningful signal for achieving the purpose of eliminating interference signal. There are many means and methods to eliminate interference factors during the development process of eddy current testing, whereas the ECT technology does not make a significant breakthrough nor achieve wide applications until Dr. Forster brought impedance analysis into it [7-10].

So far, the impedance analysis method is still the most widely applied method in eddy current testing. Impedance analysis will be discussed in below [11].

#### (1) COIL IMPEDANCE

The probe coil of eddy current testing is the key to ECT system, and it is wound by metal wires. Probe coil not only has inductance, but also has resistance and capacitance. Therefore, the coil can be represented by a series circuit of inductors, capacitors and resistors, while it may usually ignore the distributed capacitance between turns. The complex impedance of coil itself can be expressed in the following equation:

$$Z = R + j\omega L$$

(1)

In eddy current testing, under the effect of current-carrying detecting coil, the eddy current of a specimen, which induced due to electromagnetic induction is just like the current flowing through the multilayer dense stacked coil. By doing this, the detected metal specimen can be seen as a secondary coil which linked by detection coil. Consequently, considering from the perspective of circuits, ECT is similar to the case of coupled inductance circuit, and the analysis of detecting coil impedance in eddy current testing can be discussed under the situation which is similar to two coupled coils [12].

An eddy current testing system can be equivalent to the equivalent circuit consisting of two inter-coupling coil, which is shown in Fig. 1. When an alternating current  $I_1$  passes through the primary side coil, the primary side coil is going to induce an alternating electromagnetic field, and the secondary side is going to induce a current to the effect of the electromagnetic field. At the same time, the induced current in a secondary side coils reacts upon the primary side through mutual inductance; in this case, the equivalent impedance can be used to express the effect on the primary side coil which is exerted by the secondary side coil.



Fig. 1: Mutual inductance circuit of coupled coils

At this moment, the impedance of coil 1 varies, the quantity of variation can be expressed with equivalent impedance  $(Z_z = R_z + X_z)$  as below:

$$R_{z} = \frac{X_{M}^{2}}{R_{2}^{2} + X_{2}^{2}} R_{2} \qquad X_{z} = -\frac{X_{M}^{2}}{R_{2}^{2} + X_{2}^{2}} X_{2}$$
(2)

where  $X_2 = \omega L_2$ ,  $X_M = \omega M$ .

The sum of equivalent impedance and primary side coil impedance is called apparent impedance  $(Z_s = R_s + X_s)$ 

$$R_s = R_z + R_1 \tag{3}$$

$$X_z = X_z + X_1 \tag{4}$$

where  $R_1 + X_1 = R_1 + j\omega L_1$  is apparent impedance of the primary side coil.

Knowing from the above definition of apparent impedance, the variation of apparent impedance to a circuit is going to draw the change of current or voltage in the primary side. As a result, the effect from the secondary side coil exerts on the primary side coil impedance can be back-stepped according to the impedance variation of the primary side circuit. Thereby, the impedance variation of the secondary side circuit can be calculated.

The value of two components  $R_s$  and  $X_s$  of apparent impedance by the primary side circuit can be achieved from reducing the value of secondary side resistance  $R_2$  constantly from  $\infty$  to zero, and draw the achieved value on a coordinate plane, which takes  $R_s$  as horizontal axis and  $\omega L$  as a vertical axis, then a semicircle curve shown in

Figure 2 will be obtained, and the curve is called impedance plane diagram. The radius to the circle in Fig. 2 equals to  $k^2 \omega L_1 / 2$ , where  $k^2 = M^2 / L_1 L_2$ . Apparent reactance  $\omega L$  monotone reduces from  $\omega L_1$  to  $\omega L_1 (1-K^2)$ , whereas apparent resistance *R* increases from  $R_1$  and after passing the maximum point  $(R_1 + k^2 \omega L_1 / 2)$ , it decreases back to  $R_1$ , the parameter is  $R_2 (\infty \rightarrow 0)$  or  $X_z (0 \rightarrow \infty)$ .



Fig. 2: Impedance plane diagram of primary side coil when coils are coupled

#### (2) SKIN EFFECT

When alternating current energizes the exciting coil, the eddy current at certain depth induced in a test piece is going to generate a magnetic field whose direction is opposite to the original magnetic field and reduce the magnetic flux, then lead in the eddy current weaken in deeper layer. As a result, the density of eddy current becomes less with the distance to the surface increases. This variation depends on excitation frequency, the conductivity and the permeability of test piece, and the eddy current induced in a test piece concentrate at the surface of a test piece near the exciting coil. This phenomenon is called skin effect. Under the circumstances of the plane electromagnetic wave permeates into a semi-infinite conductor, the attenuation formula of eddy current shows below:

$$J_{x} = J_{0}e^{-x\sqrt{\pi f \mu\sigma}}$$
<sup>(5)</sup>

In the formula, where  $J_0$  represents the density of eddy current on the surface of test piece,  $\sigma$  represents the conductivity of test piece,  $\mu$  represents the permeability of a test piece, x represents the distance to the surface of test piece,  $J_x$  represents the density of eddy current lying in the test piece at the distance of x to the surface, f represents the frequency of exciting current. In order to indicate the depth of eddy current testing, usually define the depth where the density of eddy current reduces to 1/e times of it that is on a surface of a test piece as standard penetration depth (skin depth), expressed with  $\delta$ . By equation (5):

$$\delta = \frac{1}{\sqrt{\pi f \,\mu\sigma}}\tag{6}$$

The formula is appropriate to the material of infinite thickness and the plane electromagnetic field. In the process of actual testing, the attenuation density quantity of eddy current is more than the value calculated by a skin depth formula. The difference of eddy current density indicates that the internal defects lying in different depth will change the probe impedance in varying degrees, and a big internal defect and a small external defect will generate signals of same amplitude. Therefore, it is not enough to estimate the severity of a defect only according to the change of signal's amplitude, and make accurate judgment only if analyze the change of both signal's amplitude and signal phase simultaneously.

#### EDDY CURRENT TESTING BASED ON FIELD ANALYSIS

The eddy current testing probe based on field analysis consists of a big exciting coil and one or some small magnetic-field sensors. The exciting coil is used to generate the induced eddy current in test piece, and the magnetic-field sensors are applied to measure magnetic field at each point in space. In order to facilitate, multiple magnetic field sensors can be integrated on a single substrate to constitute a coil array. The ECT field analysis mathematical model for defects in conductive structure can be regarded as a computing problem of perturbed electromagnetic field, and on the basis of scattered field distribution measured by magnetic-field sensors to derive the distribution of eddy current in a test piece, in order to identify defects, which evolves from the Maxwell's equations in essence. Consequently, this section researches from a time-harmonic electromagnetic field to a

perturbed electromagnetic field around the Maxwell's equations and their properties [13-15].

#### (1) TIME-HARMONIC ELECTROMAGNETIC FIELD MAXWELL'S EQUATIONS

When the field source varies sinusoidally in time, the stable-state electromagnetic field which is in linear medium and whose parameters do not change with time is a time-harmonic electromagnetic field. The electromagnetic field problems in eddy current testing can be simplified to analyze and solve the problems of time-harmonic electromagnetic field, besides, due to a non-sinusoidal periodic signal can be decomposed into a superposition of a series of sinusoidal signals, the solution of non-sinusoidal stable-state linear electromagnetic field can be obtained through solving the problems of time-harmonic field [16-17].

Take  $e^{j\omega t}$  as a time-harmonic factor,  $\omega > 0$ , the Maxwell's equations can be expressed into complex form in light of the corresponding relation between sinusoidal quantity and complex quantity:

$$\nabla \times \dot{H} = \dot{J}_s + (\sigma + j\omega\varepsilon)\dot{E}$$
<sup>(7)</sup>

 $\nabla \times \dot{E} = -j\omega \dot{B} \tag{8}$ 

$$\nabla \cdot \dot{B} = 0 \tag{9}$$

$$\nabla \cdot \dot{D} = \dot{\rho} \tag{10}$$

In the formula, where  $\dot{H}$  represents magnetic-field intensity,  $\dot{J}_s$  represents current density of external source,

 $\dot{D}$  represents electric displacement, B represents magnetic induction intensity, E represents electric field intensity,  $\dot{\rho}$  represents free charge volume density. The complex form constraint equations significantly reduce the complexity

of solving the solutions of field and remove the spot representing a complex number, like  $\dot{B}$  can be written as B,  $\dot{E}$  can be written as E, etc.

# (2) TIME-HARMONIC FIELD'S VECTOR MAGNETIC POTENTIAL AND ITS BOUNDARY VALUE PROBLEMS

In order to simplify the computing and analysis, we bring in vector magnetic potential A to describe the boundary value problems of time-harmonic field, so that the time-harmonic field Maxwell's equations can be expressed with A [18].

In vector analysis, it's certain for any vector A:

$$\nabla \cdot (\nabla \times A) \equiv 0 \tag{11}$$

Contrast the equation (9) of time-harmonic field Maxwell's equations, consider

$$B = \nabla \times A \tag{12}$$

Plug equation (12) into equation (8) and get:

$$\nabla \times (E + j\omega A) = 0 \tag{13}$$

In vector analysis, it's constant for any scalar function  $\phi$ 

$$\nabla \times (\nabla \varphi) \equiv 0 \tag{14}$$

Contrast equation (13) to (14), consider

$$E + j\omega A = -\nabla\varphi, \text{ or } E = -\nabla\varphi - j\omega A \tag{15}$$

here,  $\varphi$  represents scalar potential. According to equation (15) and (7), while use the relation equation  $B = \mu H$  and vector analysis formula  $\nabla \times (\nabla \times F) = \nabla (\nabla \cdot F) - \nabla^2 F$ , it can get

$$\nabla^2 A + k^2 A = -\mu J_s + \nabla (\nabla \cdot A - \frac{k^2}{j\omega} \varphi)$$
<sup>(16)</sup>

where,  $k^2 = -j\omega\mu(\sigma + j\omega\varepsilon)$ .

On the other hand, use the relation equation  $D = \varepsilon E$  and equation (15), the equation (10) can be written into

$$\nabla^2 \varphi + j\omega \nabla \cdot A = -\frac{\rho}{\varepsilon} \tag{17}$$

Equation (16) and (17) contain all the relation of Maxwell's equations (7)-(10). For sake of solving equation (16) conveniently, it chooses the electromagnetic potential function (A,  $\varphi$ ) which meets Lorentz gauge:

$$\nabla \cdot A - \frac{k^2}{j\omega} \varphi = 0 \tag{18}$$

Use Lorentz gauze, equation (16) and (17) respectively turn into:

$$\nabla^2 A + k^2 A = -\mu J_s \tag{19}$$

$$\nabla^2 \varphi + k^2 \varphi = -\frac{\rho}{\varepsilon} \tag{20}$$

After using Lorentz gauze, the inter-coupling of A and  $\varphi$  which present in origin equation (16) and (17) is separated. Vector magnetic potential A is known, and then could get the expression of scalar potential by using Lorentz gauze:

$$\varphi = \frac{j\omega}{k^2} \nabla \cdot A \tag{21}$$

plug into equation (15), so the electric field intensity also can be expressed with vector magnetic potential:

$$E = -j\omega A - \nabla \varphi = -j\omega [A + \frac{1}{k^2} \nabla (\nabla \cdot A)]$$
<sup>(22)</sup>

Equation (12) and (22) indicate that as long as determine a vector magnetic potential A uniquely, each component of electromagnetic is going to be ascertained uniquely.

#### (3) PERTURBED MAGNETIC FIELD GENERATED BY IDEAL DEFECTS

So far, there have been massive research reports about the perturbed electromagnetic field caused by ideal defects. Typical eddy current testing problems can be described in Fig. 3: the exciting coil in air domain  $V_a$  is the time-harmonic exciting source Js with factor  $e^{j\omega t}$ , and a defect  $V_f$  is surrounded by conductor  $V_c$ . Usually makes the exciting coil scan across the surface of test piece, and inspect defects through variations of scattered field. Assuming the interface between air and conductor is  $S_{ac}$ , the interface between defect and conductor is  $S_{dc}$ , the conductivity of conductor domain is  $\sigma_c$ , the conductivity of defect domain is  $\sigma_f$ , and defect fulfills with air inside. The variation of electromagnetic field to the system caused by a defect is the key to field analysis [19-20].



Define  $E^d$  and  $B^d$  as the difference between the field with defect and the field with no defect, which is:

$$\begin{cases} B_k^d = B_k - B_{ik} \\ E_k^d = E_k - E_{ik} \end{cases}$$
(23)

where k = a, c, f. We can get the equations as follows:

In air domain  $V_a$ :

$$\nabla \times B_a^d = 0 \tag{24}$$

$$\nabla \times E_a^d = -j\omega B_a^d \tag{25}$$

In conductor domain  $V_c$ :

$$\nabla \times B_c^d = \mu_0 \sigma_c E_c^d \tag{26}$$

$$\nabla \times E_c^d = -j\omega B_c^d \tag{27}$$

In defect domain  $V_f$ :

$$\nabla \times B_f^d = \mu_0 \sigma_f E_f - \mu_0 \sigma_c E_{if} \tag{28}$$

$$\nabla \times E_f^d = -j\omega B_f^d \tag{29}$$

If regard the  $(\mu_0 \sigma_f E_f - \mu_0 \sigma_c E_{if})$  in equation (28) as an equivalent current source, then the equations (24)-(29) have apparent physical meaning. It indicates the perturbed field can be regarded as being generated by equivalent current source of defect domain.

In the system described by Fig. 3, the vector magnetic potential in air generated by unit time-harmonic current dipole, which is in the conductor along x direction:

$$A_a = A_{ax}i + A_{az}k \tag{30}$$

In there

$$A_{\alpha x} = \frac{j}{4\pi\omega} \int_{0}^{\infty} \frac{2\lambda}{\lambda+\mu} e^{\mu z^{2} - \lambda z} J_{0}(\lambda\rho) d\lambda$$
(31)

$$A_{az} = \frac{j}{4\pi\omega} \cos\varphi \int_0^\infty -\frac{2\lambda}{\lambda+u} e^{uz-\lambda z} J_1(\lambda\rho) d\lambda$$
(32)

where r=(x, y, z) represents field point radius vector, r = (x', y', z') represents source point radius vector, R = |r - r'| represents the distance field point and source point,  $\rho = \sqrt{(x - x')^2 + (y - y')^2}$ ,  $\cos \varphi = (x - x') / \rho$ ,  $\sin \varphi = (y - y') / \rho$ ,  $J_0(\cdot)$  and  $J_1(\cdot)$  represent zero order and first-order Bessel function respectively,  $u = \sqrt{\lambda^2 - k^2}$ . Owing to the field, point lies in air domain and source point lies within a conductor domain, z > 0,  $z' \le 0$ .

Get the magnetic field B in air domain through vector magnetic potential A:

$$B = \nabla \times A = \frac{\partial A_z}{\partial y} i + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x}\right) j + \left(-\frac{\partial A_x}{\partial y}\right) k$$
(33)

consequently

$$B_{x} = \frac{j\sin\varphi}{4\pi\omega} \int_{0}^{\infty} \frac{2\lambda}{\lambda+u} e^{uz - \lambda z} \left[\frac{J_{1}(\lambda\rho)}{\rho} - \lambda J_{0}(\lambda\rho)\right] d\lambda$$
(34)

$$B_{y} = \frac{j}{4\pi\omega} \int_{0}^{\infty} \frac{-2\lambda^{2}}{\lambda+u} e^{u^{2}-\lambda z} \lambda J_{0}(\lambda\rho) d\lambda - B_{x} \cot\varphi$$
(35)

$$B_{z} = \frac{j\sin\varphi}{4\pi\omega} \int_{0}^{\infty} \frac{2\lambda^{2}}{\lambda+u} e^{uz^{2}-\lambda z} J_{1}(\lambda\rho) d\lambda$$

(36)

#### RELATIONS BETWEEN IMPEDANCE ANALYSIS AND FIELD ANALYSIS

In eddy current non-destructive testing, exciting coil generates induced eddy current through the conductor, and the distribution of eddy current influences the magnetic field surrounding exciting coil, which makes coil impedance engender an increment  $\Delta Z$ . When there is defect existing in the conductor, the distribution of eddy current is disturbed and varies the increment of coil impedance. On the one hand, the ECT technology based on impedance analysis identifies the defect in light of the magnitude and phase of coil impedance increment  $\Delta Z$ ; On the other hand, the magnitude of perturbed magnetic field also reflects the situation of the defect. If detecting the size and distribution of the disturbed magnetic field, and through analyzing the perturbed magnetic field, it can also realize the identification of a defect, which is the ECT technology based on field analysis.

The relations between impedance analysis and field analysis can be converted through electromagnetic field equations, and the two analysis methods not only have close connection between, but also possess their respective advantages and disadvantages in detecting process [21]. For the solving region V, there are following relations between detecting probe impedance and electromagnetic field quantity seeking for solutions:

$$\sigma^* = \sigma + j\omega\varepsilon \tag{37}$$

$$J^* = \sigma^* E \tag{38}$$

$$\nabla \times E = -\frac{\partial B}{\partial t} \tag{39}$$

$$P = \frac{1}{2\sigma} \int_{V} J \cdot J^* \mathrm{d}V \tag{40}$$

$$R = \frac{P}{I^2} \tag{41}$$

where *E* represents magnetic-field intensity, *B* represents magnetic induction intensity, *J* represents the density of current,  $\varepsilon$  represents the dielectric constant,  $\sigma$  represents conductivity, *I* represents RMS value of current, *P* represents the comic loss in a domain, *V* represents the electromagnetic field domain under solved. Using the above relations and it is possible to obtain the variation of probe impedance through the known electromagnetic field quantity in space and other electromagnetic parameters. Then connect the analysis methods based on impedance and on a field. The comparison of two methods is shown in Tab. 1.

According to the phase and amplitude of impedance increment, the ECT based on impedance analysis judges the existence of a defect in test piece and identifies the defect. Generally speaking, the response of detecting coil reaches the maximum when the coil is responding to its surrounded area and to the material able to change total magnetic flux through the coil. As a result, when find out the defect with larger size, applying coil detect and impedance analysis has more advantages. The distribution of perturbed magnetic field cannot be interpreted due to the coil impedance variation  $\Delta Z$  is just integration effect of perturbed magnetic field in detecting coil volume. When detecting the defect in multilayer conductive structure, in order to achieve greater penetration depth the excitation frequency has to be decreased, and this will reduce the amplitude of induced voltage, which means the sensitivity of a probe reduces with excitation frequency decreases. In order to solve this problem, it's good to use high-powered exciting coil, to increase the turns of coil and to enlarge the radius of the probe; but this will make the exciting coil impossible to have small size, while the inspection will not be able to obtain a high space resolution and to detect the small-size defect in deep layer.

The signal detected by ECT based on field analysis reflects the spatial distribution of magnetic field. The magnetic field with a defect detected minus the magnetic field with no defect detected is the aforementioned defect perturbed magnetic field. Through analyzing the perturbed magnetic field can realize identifying the defect. Compared to the impedance analysis method, applying the field analysis method can pick up more subtle local variation information of field quantity. At the same time, all the defect information in a sphere of action of exciting field can be analyzed through the perturbed magnetic field, and the eddy current probe can detect at a relatively faster speed, so that to increase the sensitivity, spatial resolution and detecting speed. When detecting the defect in multilayer conductive structure, combining with field analysis, use the specific magnetic-field sensors to measure the magnetic-field intensity directly with free influence from exciting frequency, which can still obtain extreme high sensitivity under

low frequency; the sensors can be made quite small at the same time, and the detecting signal distortion is also very little, so it's able to detect the small-size defect in deep layer.

Detection method	ECT based on field analysis	ECT based on impedance analysis	
Detection object	space magnetic field B	coil impedance increment $\Delta Z$	
Probe layout	exciting probe and detecting probe are separated, exciting probe use coil sensor, detecting probe use magnetic field sensor, very small size, able to constitute an array	exciting coil and detecting coil can be separated or be united as one, exciting probe and detecting probe both use coil sensor, relatively larger size	
Probe detection situation	relatively high scan speed	relatively low scan speed	
Spatial resolution	spatial resolution equals to scale of magnetic field sensor, subtle, able to detect small-size defect	spatial resolution equals to scale of coil, unsubtle, unable detect small-size defect	
Defect identification	analyze the distribution of space magnetic field, good performance at low frequency, greater penetration depth, identify defect in deep layer	analyze the impedance plane diagram, low sensitivity at low frequency, only able to detect the defect on surface and near surface	
Direct problem	solve the distribution of space magnetic field from source (exciting source, defect), only need to solve eddy current field problems once in each time of analysis	solve the distribution of space magnetic field from source (exciting source, defect) and then solve coil impedance, need to solve eddy current field problems many times in each time of analysis to get impedance curve	
Inverse problem	solve the source from the distribution of space magnetic field, the corresponding relation is relatively direct	solve the source from coil impedance variation, the corresponding relation is not direct	

Tab. 1:	Comparison	of impedance	analysis and	field analysis
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#### CONCLUSION

This paper mainly researches on the theoretical basis of eddy current testing, and lays stress on discussing the two common analysis methods in ECT: impedance analysis method and field analysis method, then analyzes and contrasts the two methods in depth, while puts forward the inner connection of two methods and their respective characteristics. Due to the difference of detecting device, the ECT based on field analysis has higher sensitivity, spatial resolution and speed in detection than the ECT based on impedance analysis.

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